# (12) UK Patent Application (19) GB (11) 2 368 329 (13) A

(33) GB

(43) Date of A Publication 01.05.2002

(21)	Application	No	0128538.6
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(22) Date of Filing 31.08.1999

Date Lodged 29.11.2001

(30) Priority Data

(31) 9819118

(32) 03.09.1998

9823030

(32) 22.10.1998

(31) 9823142

(32) 23,10,1998

(62) Divided from Application No 9920329.1 under Section 15(4) of the Patents Act 1977

(51) INT CL7 B63B 21/22

(52) UK CL (Edition T) **B7V VHG V301 V309** 

(56) Documents Cited **GB 2317153 A** 

(58) Field of Search UK CL (Edition T) B7V VHG INT CL7 B63B 21/22 21/24 Online EPODOC JAPIO WPI

### (71) Applicant(s)

John Stephen Baross The Old Brewery, Urquhart Road, OLDMELDRUM, Aberdeenshire, AB51 OEX, United Kingdom

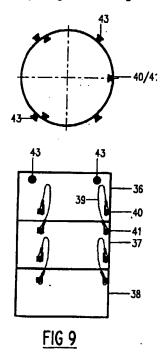
Robin Stuart Colquhoun Crosshill Cottage, Craigdam by Tarves, ELLON, Aberdeenshire, AB41 7NR, United Kingdom

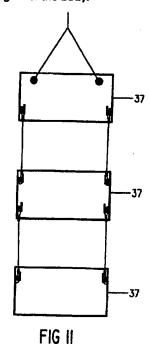
(72) Inventor(s) John Stephen Baross **Robin Stuart Colquhoun** 

(74) Agent and/or Address for Service **Murgitroyd & Company** Scotland House, 165-169 Scotland Street, **GLASGOW, G5 8PL, United Kingdom** 

#### (54) Abstract Title Removable suction anchor

(57) A subsea suction anchor for anchoring in a subsea surface comprises a plurality of portions 36, 37 and 38 which are capable of transformation from a first configuration Fig 9 in which the portions are substantially adiacent to each other to a second configuration Fig 11 in which the portions are substantially spaced apart from one another, such that the anchor can be removed from the subsea surface. A method of using said anchor is also claimed. The suction anchor may have a substantially cylindrical body having a longitudinal axis, with the portions comprising discrete longitudinal lengths of the body.





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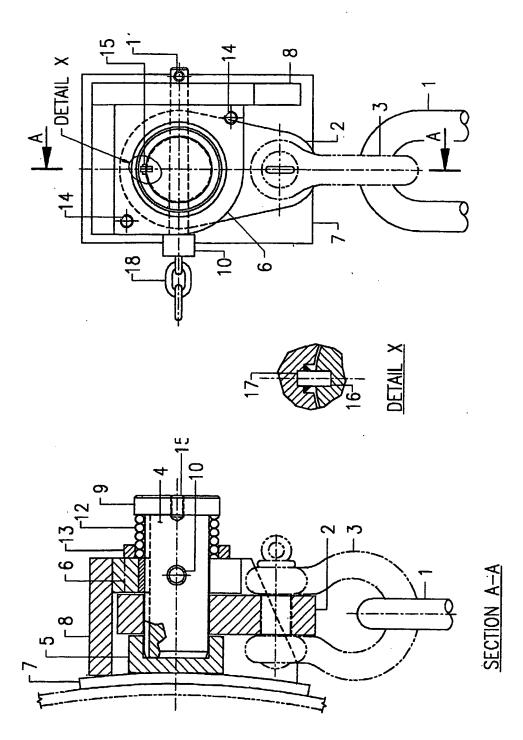
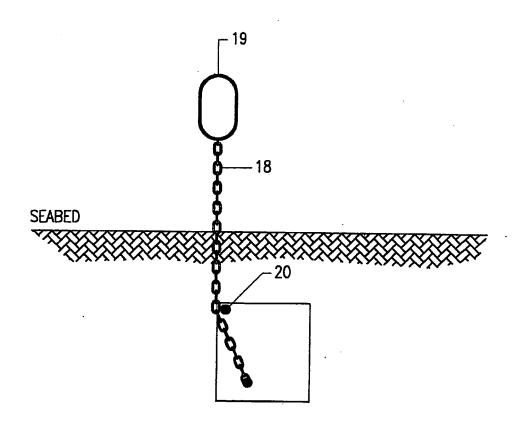
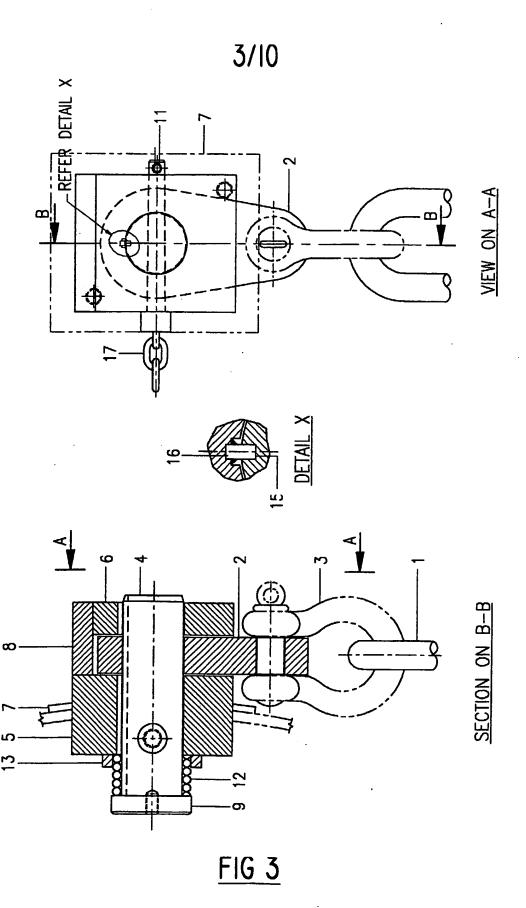
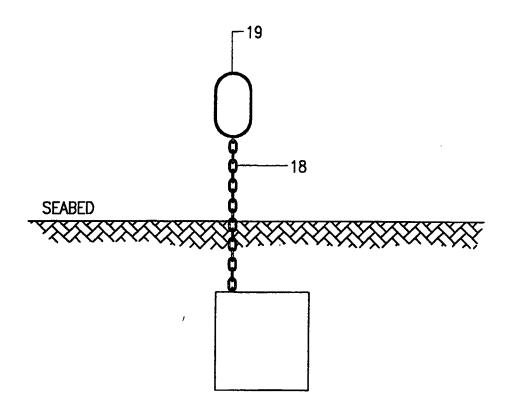
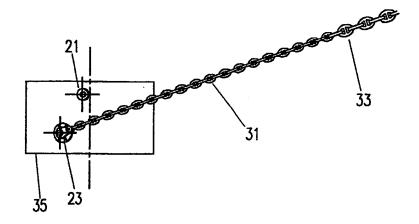


FIG I









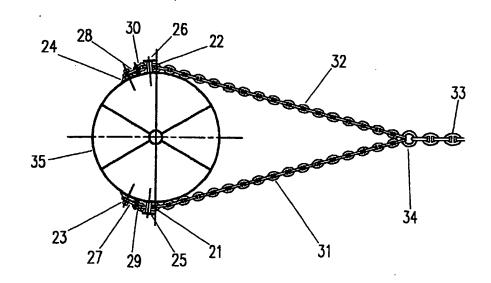


FIG 5

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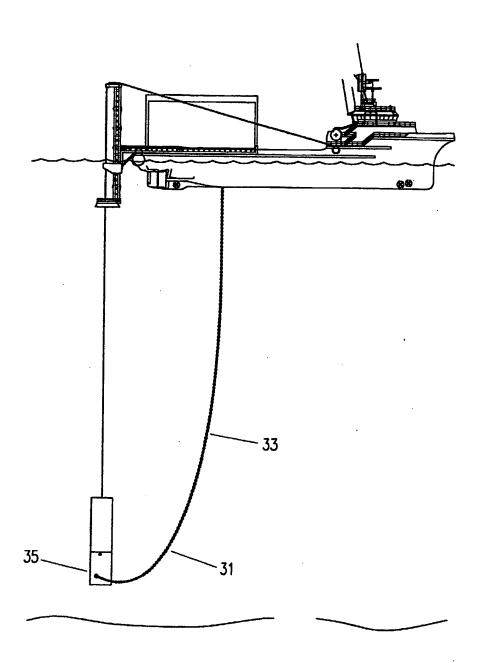
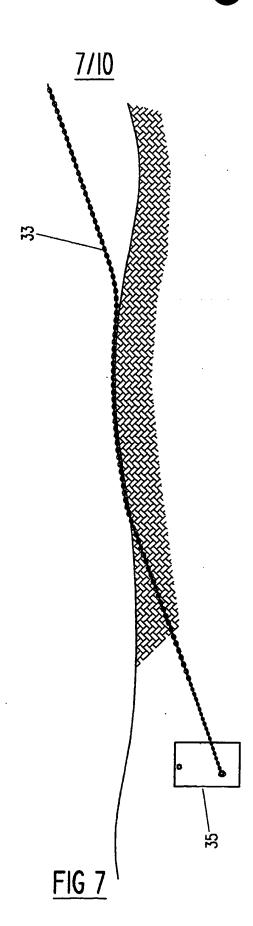
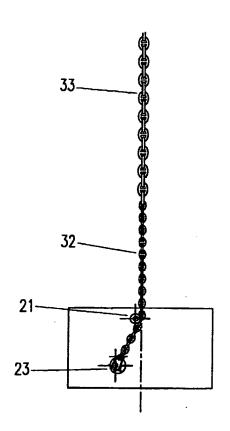
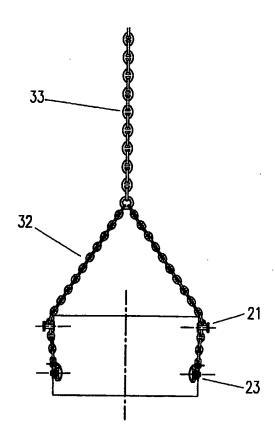
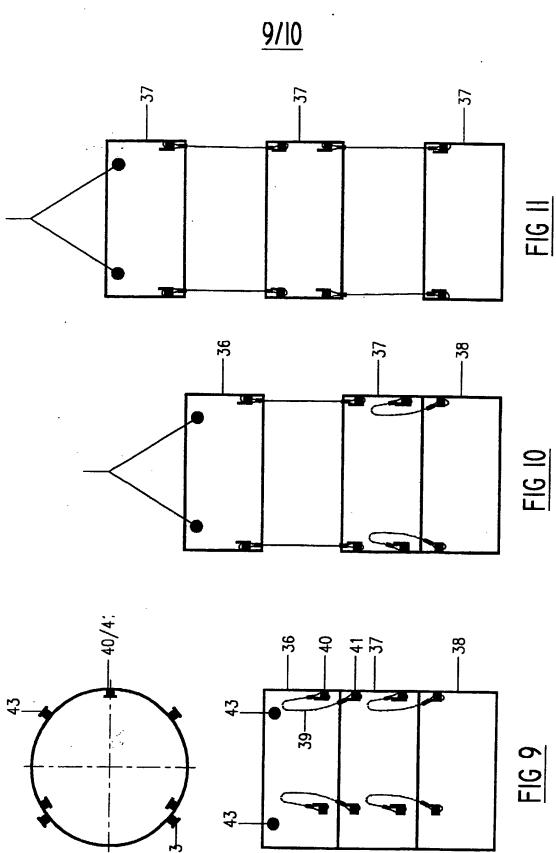


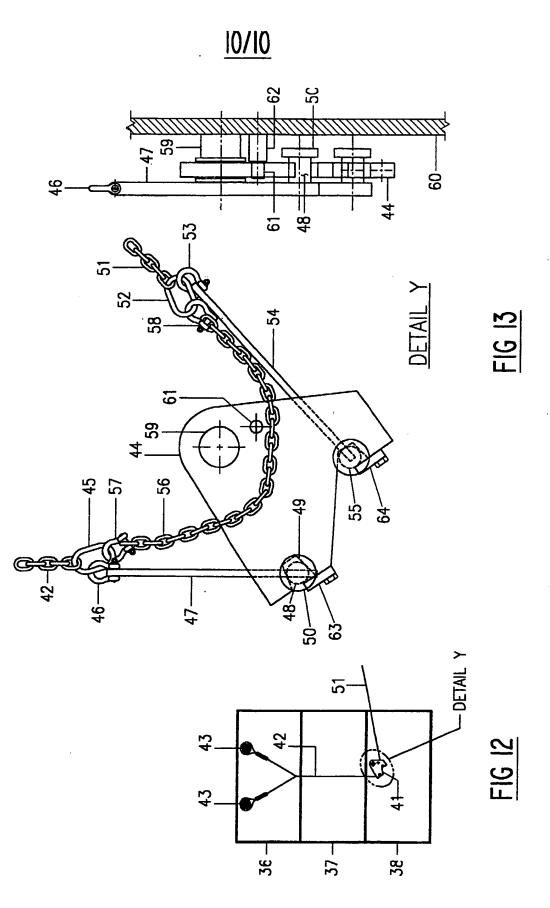
FIG 6











Removable Suction Anchor 2 3 The invention relates to a removable suction anchor 4 with minimal subsea intervention or without the need for subsea intervention. The invention in its 5 various forms is particularly suited for use with 6 anchors installed by methods other than by drag 7 embedment where the cost of vessel deployment and 8 the retrieval process is usually more than the 9 capital value of the anchors themselves. 10 11 The present invention describes methods of anchor 12 retrieval or abandonment which do not require 13 expensive subsea intervention. They will be useful 14 15 especially (though not exclusively) in connection 16 with the disconnection and recovery of mooring chains and ropes and rigging from fully buried 17 18 suction anchors. 19 20 According to a first aspect of the present invention 21 there is provided a subsea suction anchor apparatus which, in use, is anchored in a subsea surface, the 22 23 suction anchor comprising a plurality of portions which are capable of transformation from a first 24

	1	configuration in which the portions are
	2	substantially adjacent one another to a second
,	3	configuration in which the portions are
	4	substantially spaced apart from one another such
	5	that the suction anchor is capable of being removed
	6	from the subsea surface.
	7	
	8	According to a second aspect of the present
,	9	invention there is provided a method of removing a
1	10	subsea suction anchor from a subsea surface, the
1	11	method comprising providing a plurality of suction
1	12	anchor portions which are capable of transformation
1	13	from a first configuration, in which the portions
1	14	are substantially adjacent one another and in which
· 1	15	the suction anchor is capable of being used as a
1	16	suction anchor, to a second configuration in which
1	17	the portions are substantially spaced apart from one
1	18	another, and transforming the suction anchor from
1	19	the first to the second configuration.
2	20	
2	21	Mooring Anchor Disconnection System
2	22	
2	23	This is a system of devices and arrangements to
2	24	enable a mooring line or mooring line bridle to be
2	25	disconnected from an anchor which is a member of a
2	26	vessel mooring array when extraction of the anchor
2	27	is not required or is not possible. The anchor may
2	28	be a suction anchor with a fully buried lower
	29	section or may be a traditional suction anchor or a
3	30	plate anchor or traditional pile.
•	2 1	

A specific embodiment of the system for use with a 1 2 suction embedded caisson anchor will now be described by way of an example with reference to the 3 accompanying drawings in which: 4 5 6 Fig. 1 shows the general arrangement of the invention with an externally mounted spring-7 8 loaded pin assembly. 9 Fig. 2 shows an external rigging arrangement. Fig. 3 shows an alternative arrangement in 10 which the spring, taper pin, and stubshaft head 11 are on the inside of the suction anchor can 12 instead of the outside. 13 14 Fig. 4 shows an internal rigging arrangement. 15 16 The mooring line bridle wire or chain (1) is 17 connected to a rotating padeye unit (2) by a shackle 18 (3). The rotating padeye unit (2) is mounted on a 19 stubshaft (4). The stubshaft (4) spans in double 20 shear between two journal blocks (5) and (6). 21 inner journal block (5) is welded to a doubler plate 22 (7) which in turn is welded to the suction anchor 23 The outer journal block (6) is supported on 24 and welded to a steel cylinder or box (8) which is 25 in turn welded to the doubler plate (7). Slightly 26 more than one quarter (90°) of the cylinder or box (8) is cut away or open to allow access of the chain 27 (1) from directions ranging from horizontal to 28 29 vertical. The stubshaft (4) extends through and projects beyond the outer journal block (6) and 30 31 terminates in a head (9). The stubshaft (4) is held in position by a tapered pin (10) which passes 32

1	through the journal block (6) and the stubshaft (4)
2	and the cylinder or box (8) and is in its turn held
3	in position by a shearpin (11). A helical spring
4	(12) is mounted on the stubshaft between the outer
5	journal block (6) and the stubshaft head (9). A
6	retaining ring (13) may be welded to the outer
7	journal block to assist in locating the spring
8	during assembly. The spring (12) is compressed by
9	forcing the stubshaft home with the aid of a
10	hydraulic jack and strongback bearing against
11	tension bolts set temporarily into the tapped holes
12	(14). The stubshaft (4) has a keyway (15) which
13	engages with a key (16) on the outer journal block
14	(6) in order to ensure that the holes in the
15	stubshaft and journal block are properly aligned to
16	accept the tapered pin. The tapered pin (10) is
17	then inserted and the shearpin (11) in its turn is
18	inserted into the tapered pin to hold it in place.
19	The jack can now be released and the bolts removed
20	from the tapped holes. An actuation chain (18) is
21	attached to the head of the tapered pin (10). The
22	actuation chain terminates in a subsea buoy (19) as
23	indicated in Fig. 2. The actuation chain (18) is
24	sufficiently long to enable the buoy (19) to remain
25	well above seabed level after the suction anchor has
26	been installed.
27	
28	When the suction anchor has fulfilled its purpose
29	and is to be abandoned, the mooring is disconnected
30	by attaching a winch line from a surface vessel to
31	the actuation chain (18) with the aid of a WROV
32	(Working Remotely Operated Vehicle) and applying a

tension which exceeds the shearing load of the 1 2 shearpin (11) and the friction between the tapered 3 pin and the stubshaft and journal block and thereby 4 extracts the tapered pin (10) allowing the spring to 5 push the stubshaft (4) out from the journal blocks (5) and (6) sufficiently to release the rotating 6 7 padeye unit (2). The mooring chain and bridle (1) with the shackle (3) and rotating padeye (2) can now 8 be recovered leaving the suction anchor in place. 9 10 An alternative arrangement in which the spring, 11 12 taper pin, and stubshaft head are on the inside of the suction anchor can instead of the outside is 13 14 shown in Fig.3. 15 16 Mooring Line Removal Together with a Caisson or Plate Anchor Without Subsea Intervention: 17 Method 1 18 19 20 This is a system of devices and arrangements to 21 enable a mooring line to be recovered together with its associated caisson anchor or plate anchor which 22 is a member of a vessel mooring array to be 23 24 extracted from the seabed by vertical tension on the mooring line from a surface recovery vessel when its 25 26 use as a mooring anchor at the location in question 27 has come to an end. 28 29 A specific embodiment of the system for use with a 30 suction embedded caisson anchor will now be described by way of an example with reference to the 31 32 accompanying drawings in which:

1 Fig. 5 shows the general arrangement of the 2 system. Fig. 6 shows a modular suction anchor being deployed to the seabed with the mooring chain 5 rigged. 6 Fig. 7 shows the suction anchor and mooring 7 chain in normal use. Fig. 8 shows the mooring chain engaging in the 9 10 upper bosses prior to removal of the anchor. 11 Referring to the drawings, a pair of bosses (21) and 12 (22) is attached to the outside of the suction 13 anchor close to its top on opposite meridians 14 perpendicular to the direction of the mooring line 15 when it is in use as such. A second pair of bosses 16 (23) and (24) is attached to the outside of the 17 suction anchor slightly below its mid-height on 18 meridians which are offset from the meridians of the 19 20 upper bosses in a circumferential direction away 21 from the direction of the mooring line when it is in use as such. The upper bosses (21) and (22) are 22 fitted with widened heads (25) and (26). The lower 23 bosses are fitted with steel rotating padeye plates 24 (27) & (28) and shackles (29) and (30) securing the 25 mooring bridle chains (31) and (32). The bridle 26 27 chains are connected to the lead chain or rope of the mooring line (33) via a standard master link 28 29 (34).30 The sequence of operation is shown in Figs. 6, 7 & 31 The suction anchor is deployed to the seabed

with the mooring line attached to it via the bridle 1 chains. The mooring line leader (chain, wire rope, 2 3 or polymer rope) hangs from the surface well clear of the suction anchor deployment winch line and on 4 its intended operational azimuth from the suction 5 anchor axis. When the suction anchor has been 6 installed into the seabed, the mooring line leader 7 is buoyed off to await the arrival of the floating 8 unit which is to use the mooring. When the floating 9 unit has arrived and its mooring cable has been run 10 out and connected to the mooring line leader, the 11 mooring table is tensioned. This brings the bridle 12 into the configuration shown in Fig. 7. This is the 13 operational configuration of the anchor and mooring. 14 15 When the floating unit has completed its task at the 16 location and the mooring cable has been disconnected 17 from the mooring line leader, the leader and anchor 18 are recovered by an anchor handling tug or other 19 20 suitable vessel. This is done by attaching the 21 vessel winch line to the leader and applying a vertical tension. The configuration of the bridle 22 changes to that shown in Fig. 4. The bridle chains 23 come into contact with the upper bosses. In this 24 way the resultant vertical force is applied on the 25 axis of the suction anchor. Any small deviation of 26 the suction anchor from the vertical during 27 extraction will thus result in an opposing couple 28 formed by the applied force and the vertical soil 29 resistance so that the deviation will be self-30 righting. 31

1	When the anchor has been extracted it may continue
2	to hang vertically from the mooring line or may tip
3	and hang with its axis horizontal. Its orientation
4	is immaterial to its recovery over the stern roller
5	of the vessel.
6	
7	Mooring Line Removal Together with a Caisson or
8	Plate Anchor Without Subsea Intervention: Method 2
9	
10	This version of the invention is a system of devices
11	and arrangements to enable a caisson anchor or plate
12	anchor to be extracted from the seabed without
13	subsea intervention. This is achieved by pulling
14	vertically on the mooring line. The pull forces
15	required are kept within the limits of vessels and
16	winches of limited capacity by arranging for each
17	section or ring of the anchor to be extracted from
18	the seabed one after the other so that the force
19	required to pull out the whole anchor at once is not
20	needed.
21	
22	A specific embodiment of the invention for use with
23	a specially configured suction embedded caisson
24	anchor will now be described by way of an example
25	with reference to the accompanying drawings in
26	which:
27	Fig. 9 shows the general arrangement of the
28	invention in elevation and plan.
29	Fig. 10 shows the general arrangement of the
30	invention with the top ring section pulled
31	from the remaining two sections of the anchor.

1 Fig. 11 shows the general arrangement of the invention with the all ring sections 2 3 separated. Fig. 12 shows the general arrangement of the 4 invention with chains and rotating link plate 5 6 attached. 7 Fig. 13 shows the detail of the rotating link 8 plate in plan and elevation. 9 10 The rings (36), (37), and (38) of the lower anchor 11 (three rings in this example) have brackets (40) and 12 (41) between which chains (39) are connected. 13 mooring line bridle is attached to two pairs of 14 trunnions (43) on the upper ring. When the mooring line is pulled vertically, the upper ring (36) is 15 lifted through the soil. The length of the 16 connecting chains (39) between the upper ring (36) 17 18 and the next ring (37) is selected so that the first 19 ring (36) is clear of the seabed before the chains become taut and the second rings starts to be 20 21 lifted. Similarly the length of the connecting 22 chains between ring (37) and ring (38) is selected 23 so that ring (37) is clear of the seabed before ring (38) starts to be lifted. In this way only one ring 24 has to be moved at a time and the required tension 25 26 is very much less than would be the case if all 27 rings were lifted together. This keeps the anchor extraction operation within the winch capacity of a 28 29 larger number of vessels. 30 31 In order to ensure that the mooring line is 32 effectively attached to the suction anchor at the

correct height during its functioning as a mooring, 1 and in order to ensure that there is a pretension 2 between the rings to keep them together when mooring 3 load is applied, the mooring line bridle is rigged 4 to the trunnions (43) in the manner shown in Figs. 4 5 and 5. Each of the chains (42), which are bridled 6 to the trunnions (43) at their upper ends, is 7 attached at its lower end via a master link (45) and 8 shackle (46) to a steel plate strap (47) with a boss 9 (48) at its lower end. The boss (48) fits into a 10 recess (49) in a rotating link plate (44). 11 link plate rotates on a boss (59) which is welded to 12 the suction anchor wall (60) (if necessary via a 13 double plate). The link plate is initially 14 restrained from rotation by a shear pin (61) on a 15 block (62) which is likewise welded to the suction 16 anchor wall. The mooring line bridle chain (51) is 17 likewise connected via a master link (52) and 18 shackle (53) to a steel plate strap (54) carrying a 19 boss (55) at its lower end. The boss (55) fits into 20 a recess in the plate (44) in the same manner as 21 boss (48). Both bosses have heads (50) to prevent 22 them from sliding laterally from the recesses. 23 There are spring strips (63) and (64) to retain the 24 bosses (48) and (55) in their recesses. 25 spring strips are designed so as to allow the bosses 26 to be pulled from the recesses when the pull applied 27 to them has the appropriate direction and exceeds a 28 given threshold value. There is a short length of 29 loose chain (56) connected between master links (45) 30 and (52) via shackles (57) and (58). 31

1	When the suction anchor is installed, the mooring
2	bridle chains (51), which are connected to the
3	mooring leader chain, are vertical at the link
4	plate. However, the tensions applied to the bridle
5	(mainly from the buoy at the top of the leader chain
6	and from soil friction during anchor installation)
7	are insufficient to shear the pin (61). When the
8	mooring leader chain is connected to the main
9	mooring line of the vessel to be moored and the
10	vessel winches in the catenary line, the angle of
11	departure of the bridle moves progressively from the
12	vertical as the tension increases. When the mooring
13	line has reached its operational configuration, the
14	departure slope of the bridle at the link plate is
15	relatively flat (typically 15° to 30° depending on
16	the mooring tension and the seabed soil type). As
17	the mooring tension increases, the shear pin fails
18	and the link plate is free to rotate slightly,
19	though further rotation is prevented by the chain
20	(42) attached to the trunnions (43). The greater
21	the mooring tension, the greater the tension in the
22	chains (42) and hence the greater the pre-tension
23	between the suction anchor rings holding them firmly
24	together and making them act as a unit
25	notwithstanding that they are not welded together.
26	The rings are prevented from horizontal sliding
27	relative to each other by the joint arrangements
28	described in the patent applications referred to
29	above.
30	
31	When the moored vessel has completed its task on

station and the mooring line has been disconnected 

from the leader chain, the bridle (51) returns to 1 the vertical at the link plate (44). Since the pin 2 (61) has by now been sheared, any vertical tension 3 on the bridle chain (51) causes the link plate (44) 4 to rotate and increasing tension causes the boss 5 (55) to be pulled from its recess. The short chain 6 (56) then becomes taut and pulls the boss (48) in 7 its turn from its recess. The bridle chains (51) 8 are now directly connected to the trunnions (43) on 9 the top ring (36) by the chains (42). Further 10 winching in and tension on the line thereafter 11 results in the ring extraction sequence shown in 12 Figs. 9, 10, and 11. 13 14 Thus, there is a system of devices described herein 15 which provide an arrangement of devices and rigging 16 enabling a mooring line and bridle to be recovered 17 from or with a cylindrical, plate or other form of 18 anchor after use. Furthermore, an arrangement of 19 devices and rigging is described which enables a 20 mooring bridle chain to be detached from an 21 abandoned cylindrical anchor caisson by the 22 application of vertical tension to an actuation 23 chain. Also, the actuation chain may be buoyed off 24 subsea or at sea level. Furthermore, the tension 25 may be applied to the actuation chain by a winch 26 line from a surface vessel, the winch line being 27 attached to the actuation chain by WROV or by diver 28 or at the surface. 29 30 In addition, the tension on the actuation chain may 31 shear a shear pin allowing extraction of a tapered 32

. ,

. 13

retaining pin thus releasing a spring-loaded 1 2 stubshaft which withdraws through a journal block and thereby in turn causes the release of the 3 rotating padeye termination of a bridle chain. 4 Furthermore, the device may be attached either to 5 the outside or to the inside of an anchor caisson. 6 Also, the spring-loaded stubshaft holding the bridle 7 chain termination may be inserted with the aid of a 8 hydraulic jack and locked by insertion of a tapered 9 retaining pin prior to anchor deployment. 10 11 12 Furthermore, bosses on the outside of a cylindrical anchor caisson are also described which may enable 13 14 the caisson to be extracted from the seabed by the application of vertical tension via the mooring 15 chain leader line, mooring chain, and mooring bridle 16 17 chain. In addition, the upper bosses may be on opposite 18 sides of the caisson close to its top and both 19 slightly offset in the same direction from the 20 transverse diametral meridian while the lower bosses 21 likewise on opposite sides are still further offset 22 both in the same direction from the plane of the 23 upper bosses. Also, the vertical tension may be 24 25 applied to the mooring chain leader line by the winch line of a surface vessel. Also, the mooring 26 bridle chains may be attached to the lower bosses on 27 either side of an anchor caisson. Furthermore, the 28 upward tension on the mooring line typically brings 29 30 the bridle chains into contact with the upper bosses thereby encouraging the vertical axis of the caisson 31 to remain close to vertical during extraction from 32

the seabed as a result of the fact that rotation due 1 to the vertical soil resistance to extraction 2 automatically generates a restoring couple. 3 There is also described an arrangement of devices 5 and rigging which may consist of an anchor caisson made up of two or more cylindrical ring sections on top of each other and rigged in such a manner as to enable the anchor ring sections to be extracted 9 sequentially from the seabed by the application of a 10 vertical tension to the mooring line. Furthermore, 11 each ring section may be connected to the next 12 section above or below it by chains attached 13 internally at 120° intervals around the 14 circumference. Also, the mooring bridle chains may 15 be attached to link plates on opposite sides of the 16 lowest ring section, the connection of each chain to 17 its link plate being via a straight steel strap with 18 a boss on one side close to the end and this boss 19 locating into a recess in the edge of the link plate 20 and being retained by a spring-loaded retainer bar. 21 Furthermore, each delta plate may be mounted on a 22 trunnion so that it is free to rotate subject to the 23 shearing of a shear pin. Also, there are typically 24 four bosses at suitable circumferential intervals on 25 the outside near the top of the upper ring section 26 and wherein bridle chains are attached to these 27 bosses via rotating padeyes, one bridle being 28 located on each side of the caisson and with the 29 bridle apex connected via a vertical link chain to 30 the link plate on the lowest ring section with the 31 aid of straps, bosses, and recesses similar to those 32

connecting the mooring bridle chains to the link 1 plates. In addition, there may be a short length of 2 slightly slack connecting chain between the 3 chain/strap junctions on the bridle chains and link 4 chains at each link plate. Also, any significant 5 tension on the mooring line in its operational 6 orientation may cause the shearing of the shear pins 7 followed by a small rotation of the link plates and 8 a tensioning of the link chains thus holding the 9 several ring sections of the anchor more firmly 10 together the greater the pull on the mooring. 11 Furthermore, a vertical tension on the mooring line 12 after shearing of the shear pins typically results 13 in free rotation of the link plates towards the link 14 15 chains followed by escape of the strap bosses from their recesses under the influence of tensions which 16 exceed the retaining capacity of the spring-loaded 17 retainer bars and are now acting in directions which 18 cause escape rather than bedding down. Furthermore, 19 20 further vertical tension on the mooring line 21 . typically causes the rigging to reorientate so that 22 the mooring line now pulls upwards on the four 23 bosses on the upper ring section via the bridle 24 arrangements thus initiating extraction of the upper 25 ring section from the seabed. In addition, the 26 internal chains connecting the ring sections are typically of such lengths that the upper ring 27 section is clear of the soil before tension is 28 applied to the second and the second is clear of the 29 soil before tension is applied to the third and so 30 forth thus ensuring that the required tension at any 31

- time is limited to that needed for the extraction of
- one ring section. 2

n + 4

### 1 Claims

2

e 6 ) C

3 1. A subsea suction anchor apparatus which, in

4 use, is anchored in a subsea surface, the suction

anchor comprising a plurality of portions which are

6 capable of transformation from a first configuration

7 in which the portions are substantially adjacent one

8 another to a second configuration in which the

9 portions are substantially spaced apart from one

another such that the suction anchor is capable of

being removed from the subsea surface.

12

13 2. A subsea suction anchor apparatus according to

14 claim 1, wherein the suction anchor comprises a

substantially cylindrical body having a longitudinal

axis, and the portions comprise discrete

17 longitudinal lengths of the body.

18

19 3. A subsea suction anchor apparatus according to

20 claim 2, wherein the portions of the suction anchor

21 are coupled to one another such that when the

22 suction anchor is in the first configuration, each

23 portion is coincident with the other portions when

24 the suction anchor is in use as a suction anchor,

and each portion is adjacent to the closest other

26 portion.

27

28 4. A subsea suction anchor apparatus according to

any of claims 1 to 3, wherein the portions of the

30 suction anchor are coupled to one another by a

31 coupling means, such that when the suction anchor is

in the second configuration, the coupling means

18 permits the portions to be spaced apart from one 1 another, such that the suction anchor may be removed 2 from the subsea surface. 3 5. A subsea suction anchor apparatus according to 5 any of claims 1 to 4, wherein an actuation means is 6 provided such that operation of the actuation means 7 permits the transformation of the suction anchor 8 from the first to the second configuration. 9 10 6. A subsea suction anchor apparatus according to 11 claim 5, wherein the actuation means comprises a 12 releasable locking means which is coupled to an 13 actuation line, such that an applied force to the 14 actuation line permits release of the locking means. 15 16 A method of removing a subsea suction anchor 7. 17 from a subsea surface, the method comprising 18 providing a plurality of suction anchor portions 19 which are capable of transformation from a first 20 configuration, in which the portions are 21 substantially adjacent one another and in which the 22 suction anchor is capable of being used as a suction 23 anchor, to a second configuration in which the 24 portions are substantially spaced apart from one 25 another, and transforming the suction anchor from 26 the first to the second configuration such that the 27 suction anchor is capable of being removed from the 28 subsea surface. 29

30

A method according to claim 7, wherein the 31 suction anchor comprises a substantially cylindrical 32

body having a longitudinal axis, and the portions comprise discrete longitudinal lengths of the body.
3
9. A method according to claim 8, wherein the

portions of the suction anchor are coupled to one another such that when the suction anchor is in the first configuration, each portion is coincident with

8 the other portions when the suction anchor is in use

9 as a suction anchor, and each portion is adjacent to

10 the closest other portion.

11

e' n C

12 10. A method according to any of claims 7 to 9,

wherein the portions of the suction anchor are

14 coupled to one another by a coupling means, such

15 that when the suction anchor is in the second

16 configuration, the coupling means permits the

portions to be spaced apart from one another, such

18 that the suction anchor may be removed from the

19 subsea surface.

20

21 11. A method according to any of claims 7 to 10,

wherein an actuation means is provided such that

23 operation of the actuation means permits the

24 transformation of the suction anchor from the first

25 to the second configuration.

26

27 12. A subsea suction anchor apparatus according to

28 claim 11, wherein the actuation means comprises a

29 releasable locking means which is coupled to an

30 actuation line, such that an applied force to the

31 actuation line permits release of the locking means.

- 1 13. Apparatus as hereinbefore described with
- 2 reference to Figs. 9 to 13 of the drawings.

- 4 14. A method as hereinbefore described with
- 5 reference to Figs. 9 to 13 of the drawings.



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Application No: Claims searched: GB 0128538.6

1 to 14

Examiner:
Date of search:

Richard Collins 22 February 2002

Patents Act 1977 Search Report under Section 17

## Databases searched:

UK Patent Office collections, including GB, EP, WO & US patent specifications, in:

UK Cl (Ed.T): B7V VHG.

Int Cl (Ed.7): B63B 21/22, 21/24.

Other: Online EPODOC, JAPIO, WPI.

### Documents considered to be relevant:

Category	Identity of document and relevant passage		Relevant to claims
A	GB 2317153 A	(KARAL) see figures 9 to 13 and related description.	-

- Document indicating lack of novelty or inventive step
   Document indicating lack of inventive step if combined with one or more other documents of same category.
- & Member of the same patent family

- A Document indicating technological background and/or state of the art.
- P Document published on or after the declared priority date but before the filing date of this invention.
- B Patent document published on or after, but with priority date earlier than, the filing date of this application.